

Dynamic Network, Grid Computing and SCARLe

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Context:

“How can we take profit of Starplane for the SCARle project ?”

- ▶ how can we take profit of dynamic network in the context of grid ?
- ▶ how this can be applied to SCARle ?

My definition:

“A dynamic network is a network where link topology can be changed. Such networks offer to build virtual circuit with specific capability upon user request.”

Why dynamic networks arose:

- ▶ Network administrator want to do Traffic Engineering for a better best-effort routing;
- ▶ Some users need Quality of Service that best-effort cannot provide (TVoip);
- ▶ Some users need high capacity and QoS (eScience);

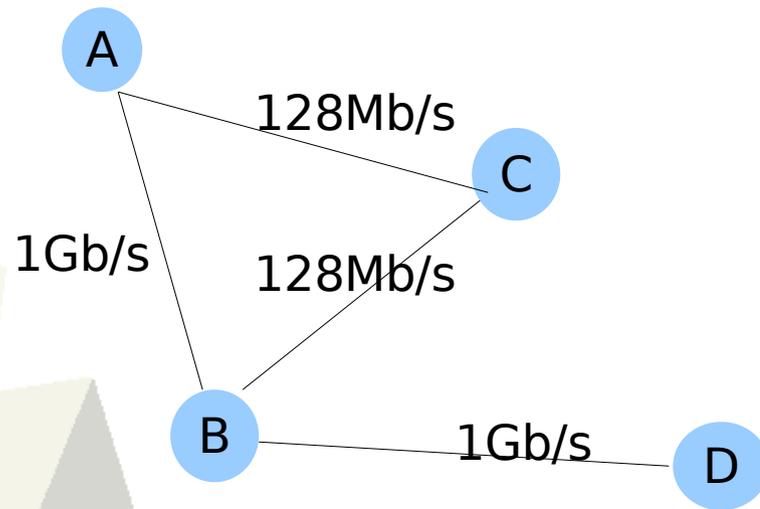
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Examples of Virtual/Dynamic Network research initiative:

- ▶ GLIF:
 - Worldwide virtual organization to promote dynamic network based on optical multiplexing.
- ▶ Surfnet6 and Netherlight:
 - Netherland hybrid network offering allocation of Lightpath upon request.
- ▶ Starplane:
 - A DAS3 dynamic network offering allocation of Lightpath upon request.

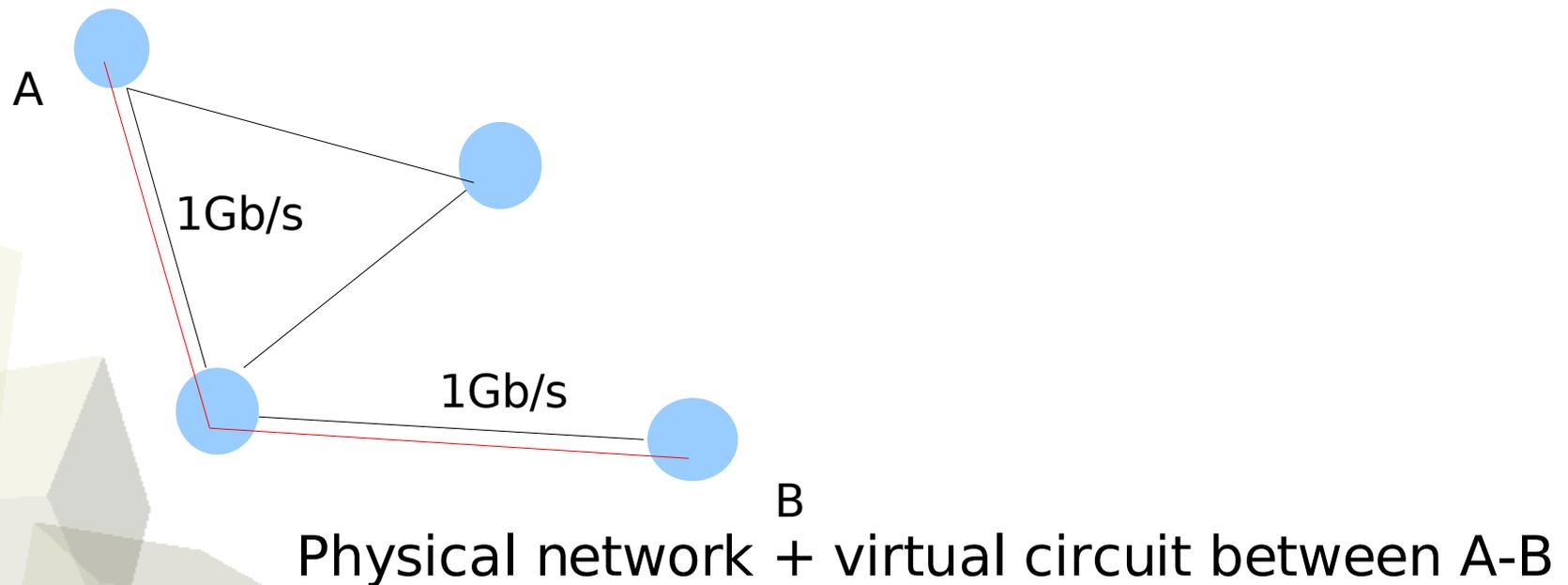
Dynamic network provides virtual circuit over physical network



Physical network

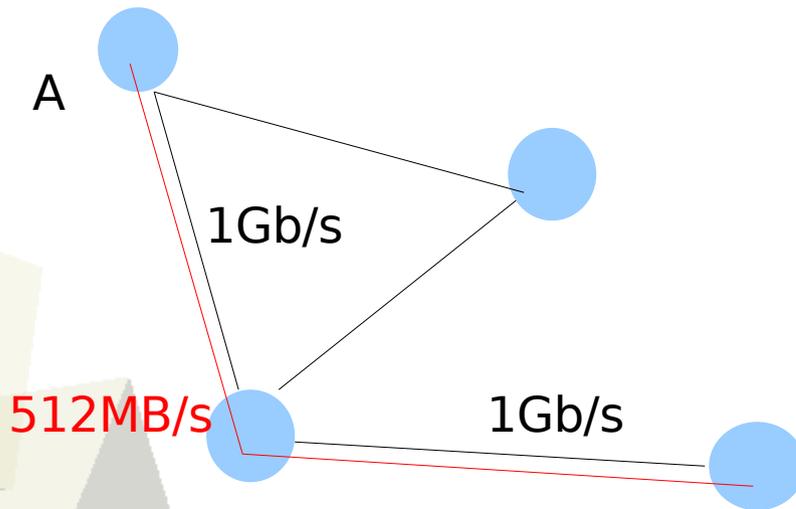
Dynamic network provides virtual circuit over physical network

Users can build their own virtual networks.



Dynamic network provide virtual circuit over physical network

Users can build their own virtual networks;
that match their Application Specific Requirement.



Physical network + virtual circuit + quality of service

To take profit of that ...

We need:

- infrastructure (they exist...see GLIF, surfnet6, Starplane);
- middleware and tools to build virtual circuit;
at least a resource-allocator/scheduler aware of network
- middleware and tools that take profit of virtual circuit;
dedicated version of GridFTP, ftp, scp over using virtual circuit to
optimize data transmission.
- API that support dynamic networks;
- software methodologies to handle the increased complexity of
dynamic network.

Scientist that want to do big science...they need to use grid and dynamic network.

We need:

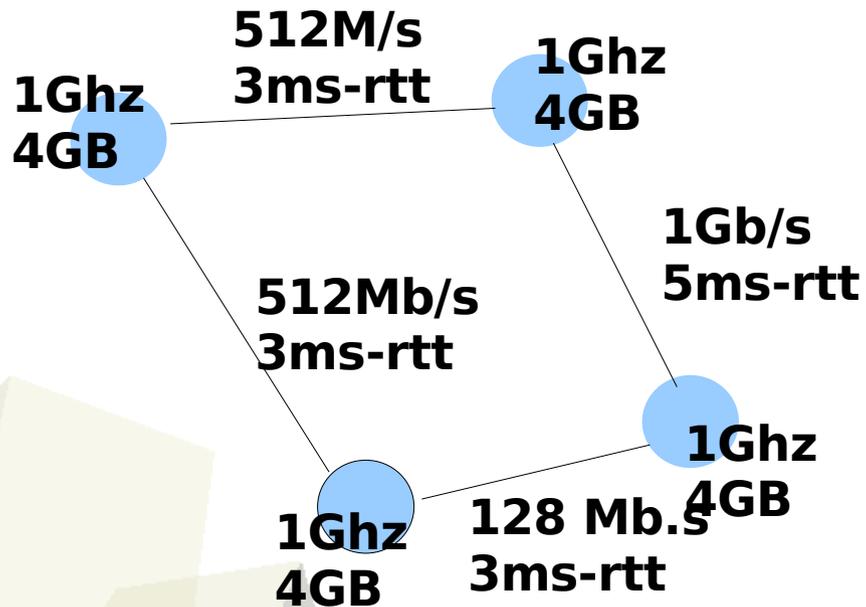
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How user of a grid could take profit of dynamic network ?

Simple model for network aware resource allocation...

Let's represent our resource by a graph:

- an node is a computation power or data storage element;
- an edge is a Virtual Path;

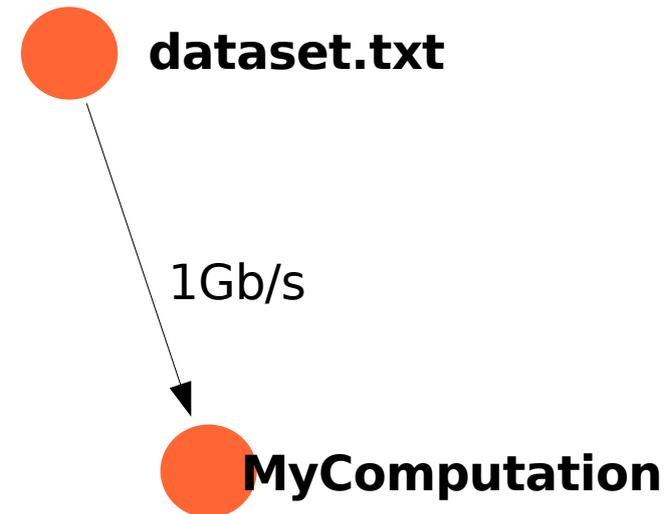
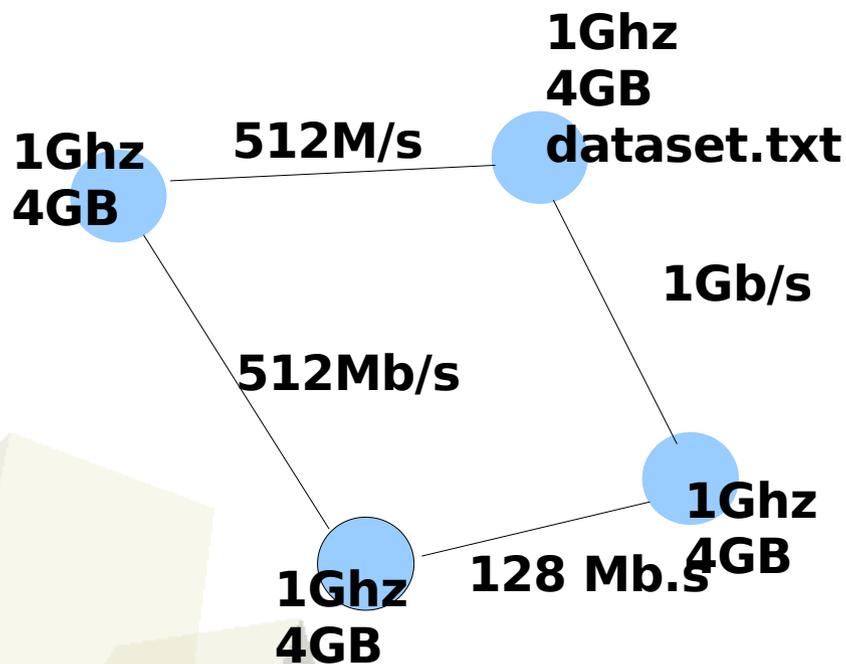


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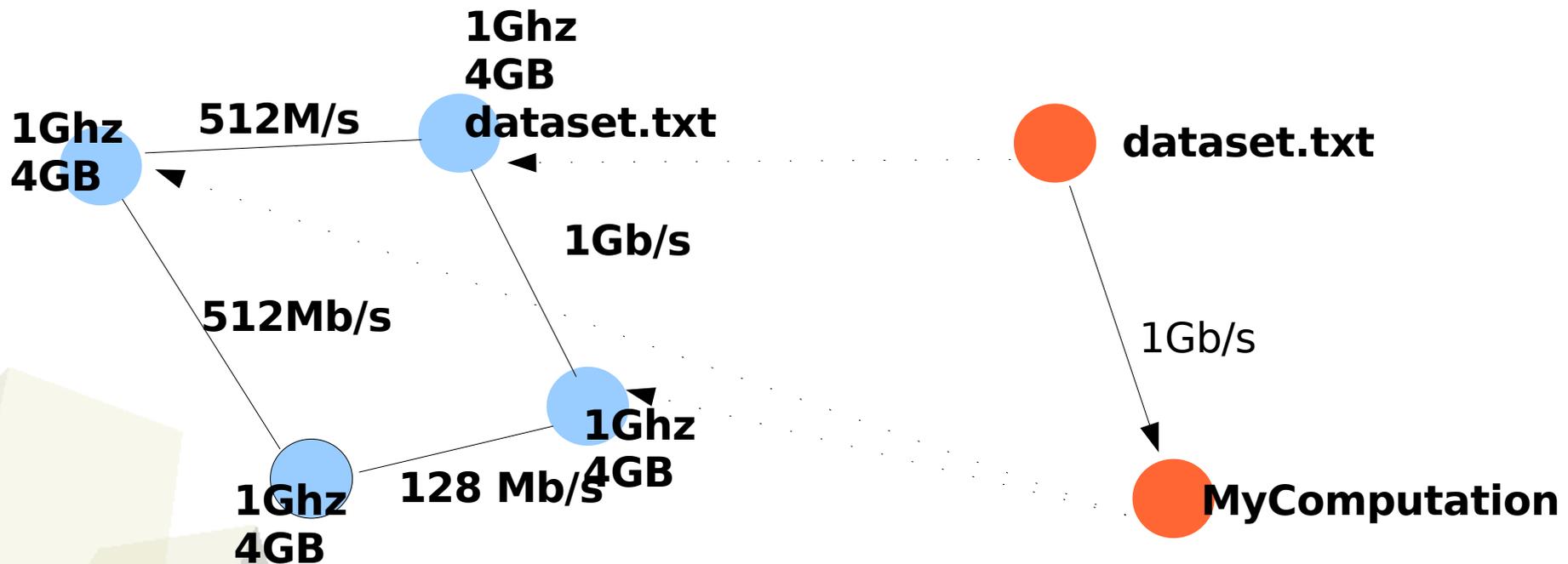
We need to map the request to the resources.

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We need to map the request to the resources.

This is a “subgraph isomorphism” test: At least NP-Complete

Don't expect an optimal solution

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We need:

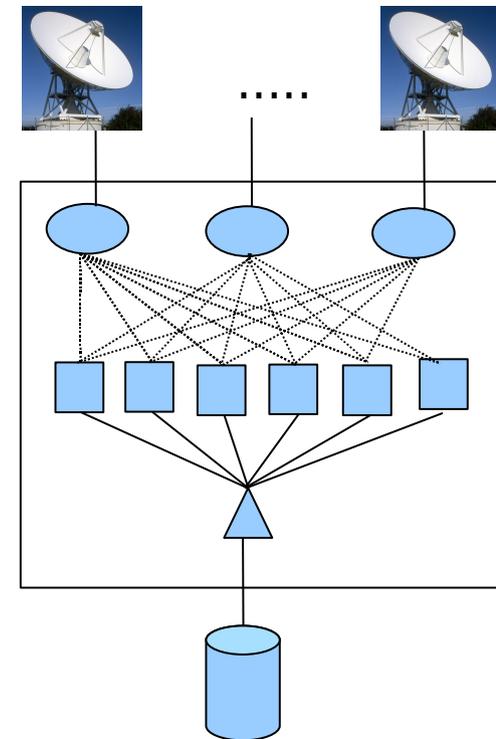
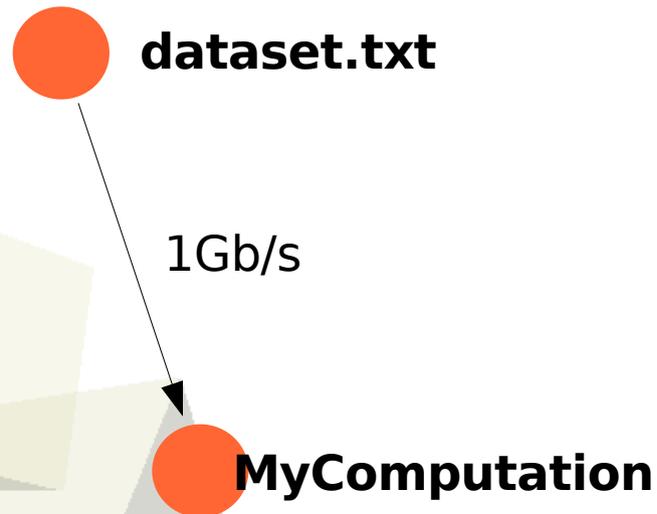
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optimize data transmission.
- API/Paradigm that support dynamic networks;

How user of a grid could take profit of dynamic network ?

Message Passing Library aware of Starplane

Message Passing Paradigm:

- the messages are explicitly exchanged between two computation elements;



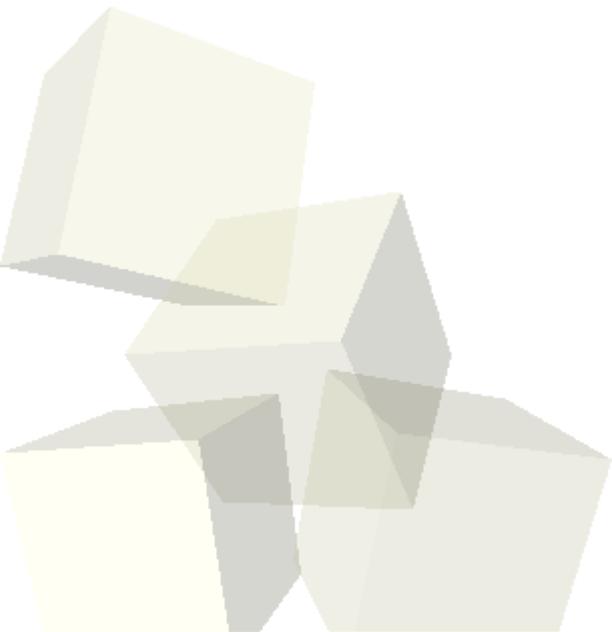
Channels:

A Channel is like a MPI_Communicator + having the ability to be bounded

to a specific resource set (device, protocol, network).

when making a software... Identify a groups of channels :

- same logical function (like MPI_Communicator)
- same requirement (bandwidth, rtt)
- between same set of processes

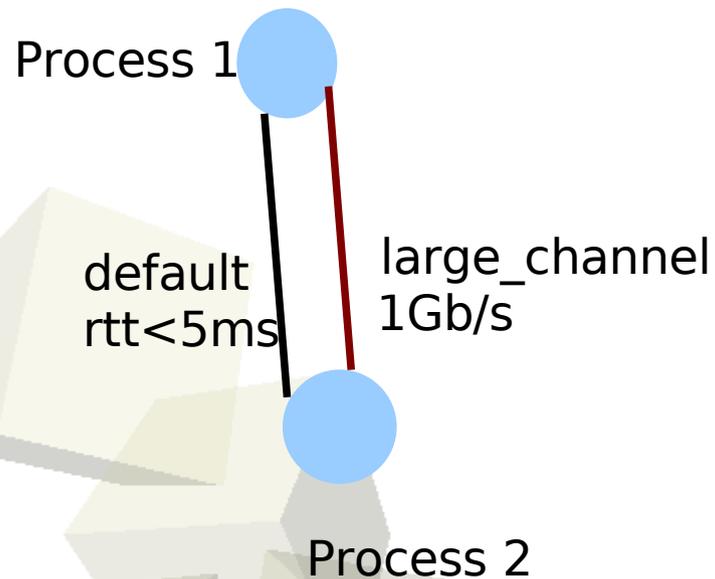


How user of a grid could take profit of dynamic network ?

Message Passing Library aware of Starplane

Methodology:

- 1) Design your application using channels (here a scp like).

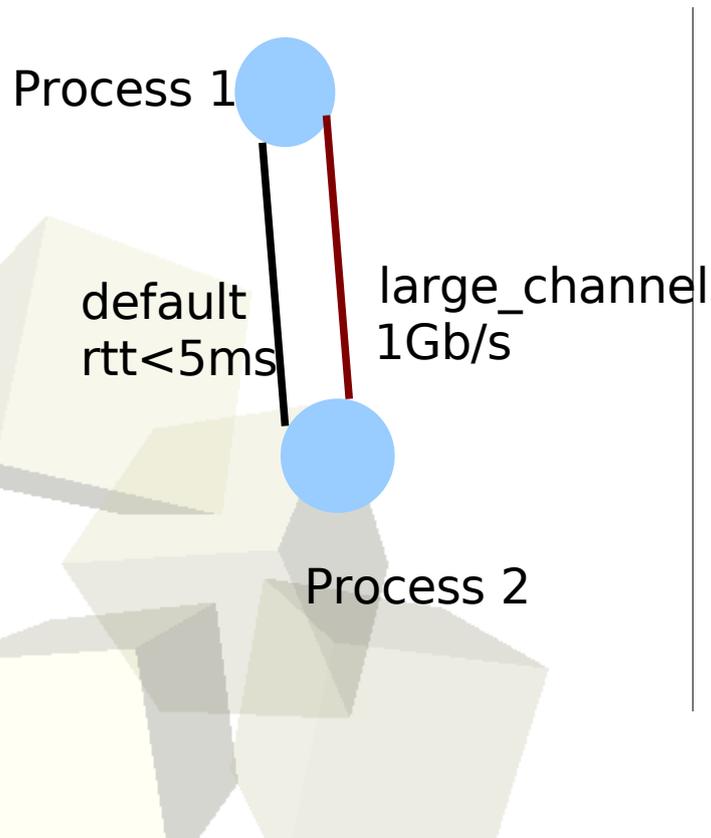


How user of a grid could take profit of dynamic network ?

Message Passing Library aware of Starplane

Methodology:

- 1) Design your application using channels;
- 2) The channel description is stored as an external file (the Application Specific Topology).



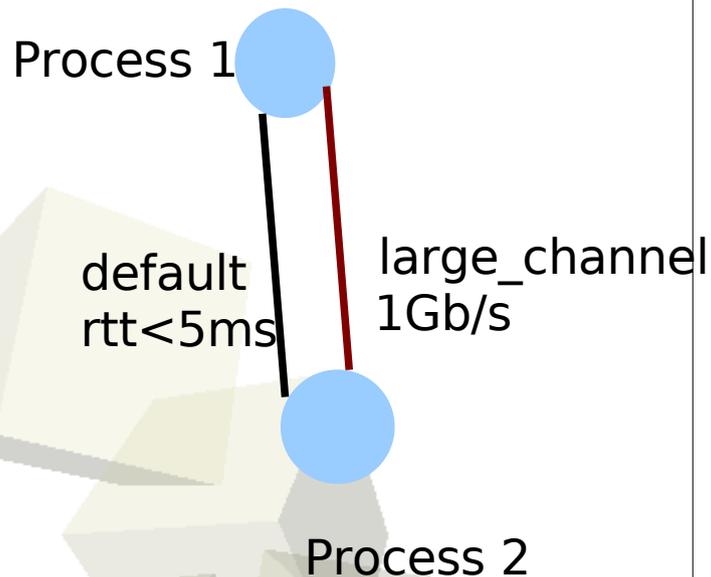
```
Process1:  
Process2:  
default_channel:  
  rtt < 5ms  
  members: Process1,  
           Process2  
large_channel:  
  bandwidth = 1Gb/s  
  members: Process1,  
           Process2
```

How user of a grid could take profit of dynamic network ?

Message Passing Library aware of Starplane

Methodology:

3) Mapping between channel and resource is done by resource allocator.



Process1:
Process2:
default_channel:
rtt < 5ms
members: Process1,
Process2
large_channel:
bandwidth = 1Gb/s
members: Process1,
Process2

Process1 map to:

Node234

Process2 map to:

Node456

default channel map to:

eth0, tcp

Node234, Node456

large_channel map to:

myrinet+starplane[red]

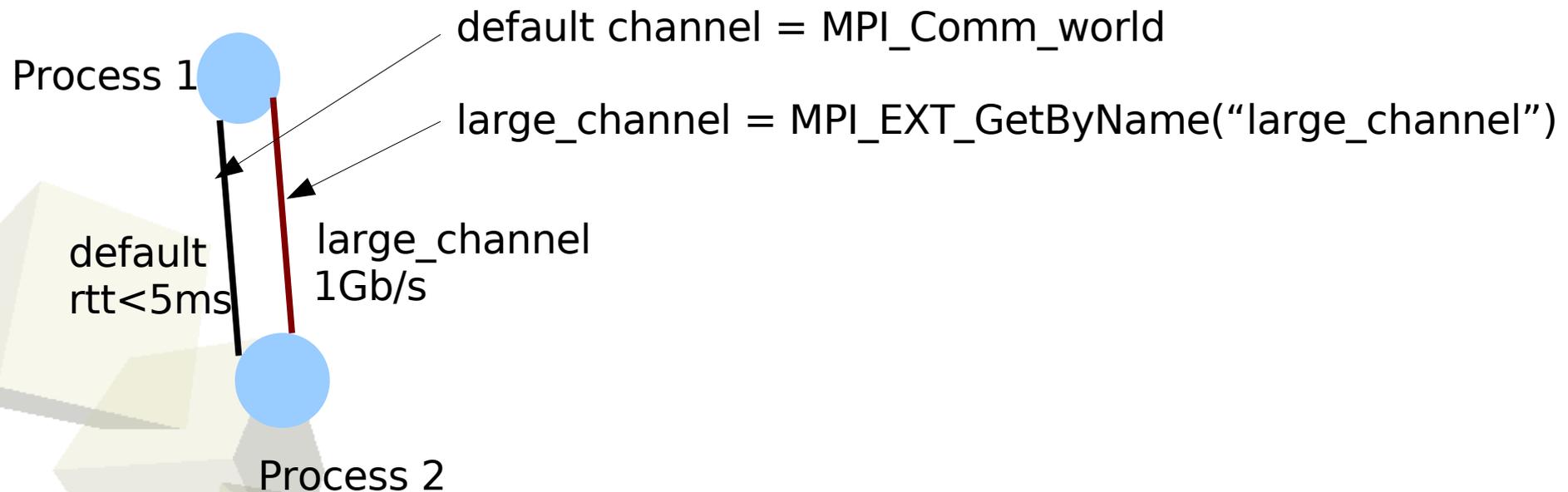
Node 234, Node456

How user of a grid could take profit of dynamic network ?

Message Passing Library aware of Starplane

Methodology:

- 3) Mapping between channel and resource is done by resource allocator.
- 4) Application is started... the mapping is loaded to initialize the physical network connexions.



The application never know what is the underlying tech

What we currently have:

- implementation of channel (with Madeleine library)
- implementation of channel over MPI (MPICH-Mad)
- some prototype of description language to request resources (
- some network resource description language (NDL is very den

What we are missing:

- a resource allocator/scheduler that map the AST to subset of M
- grid aware set of tools.

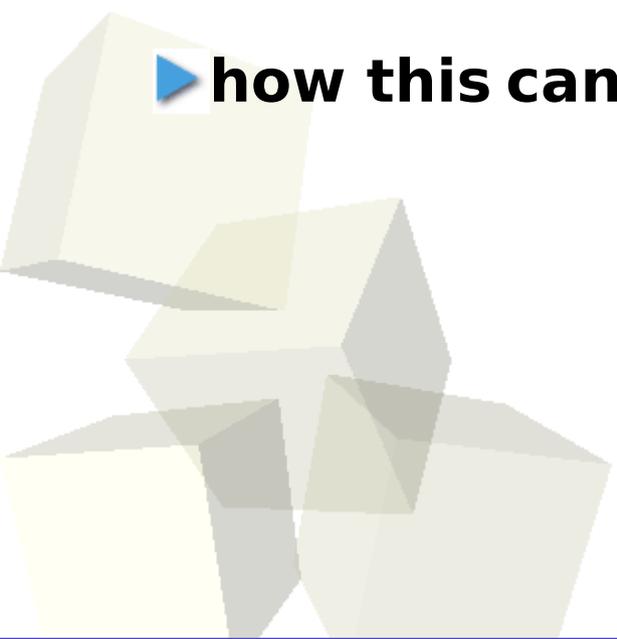


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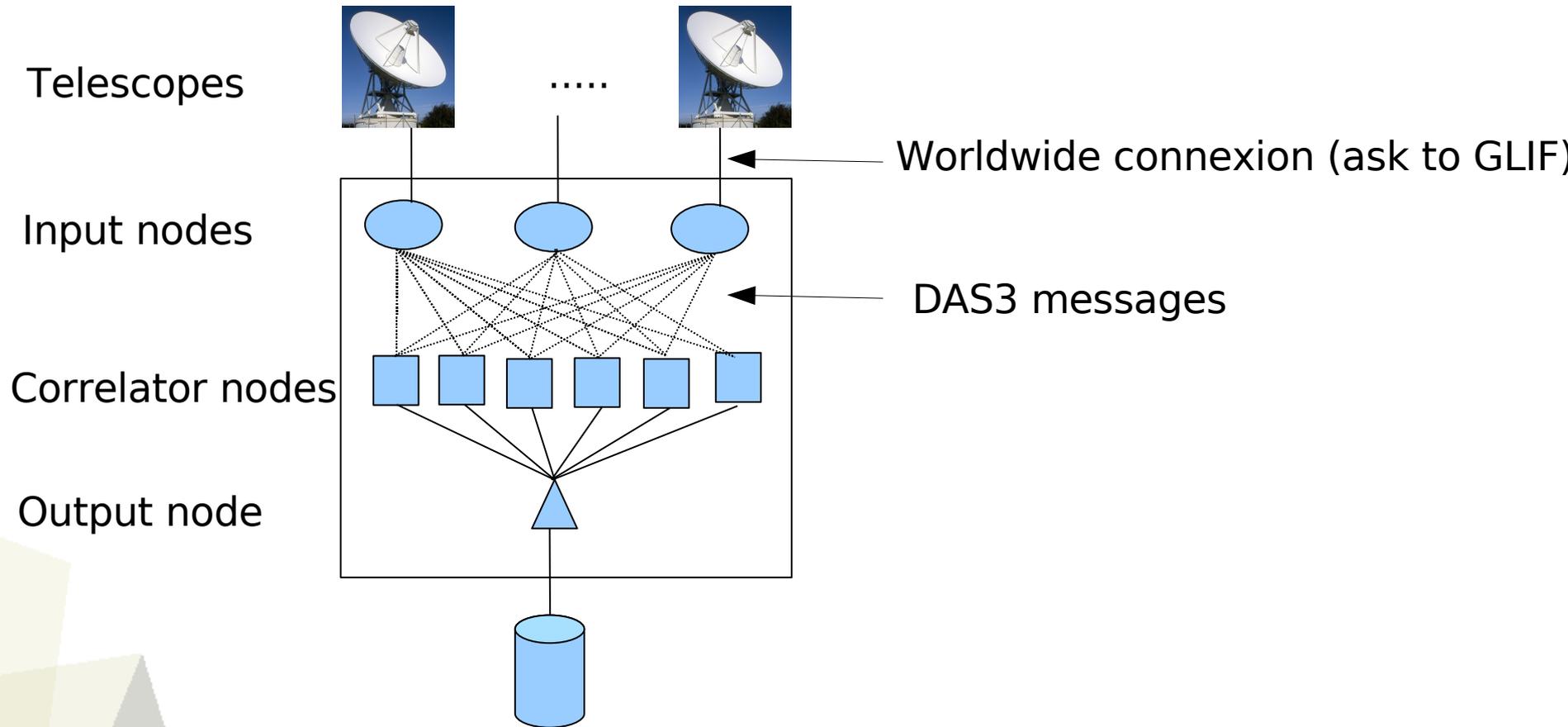
▶ how can we take profit of dynamic network in the context of grid ?

▶ **how this can be applied to SCARle ?**



SCARLe

An exemple of usage of dynamic network for static application

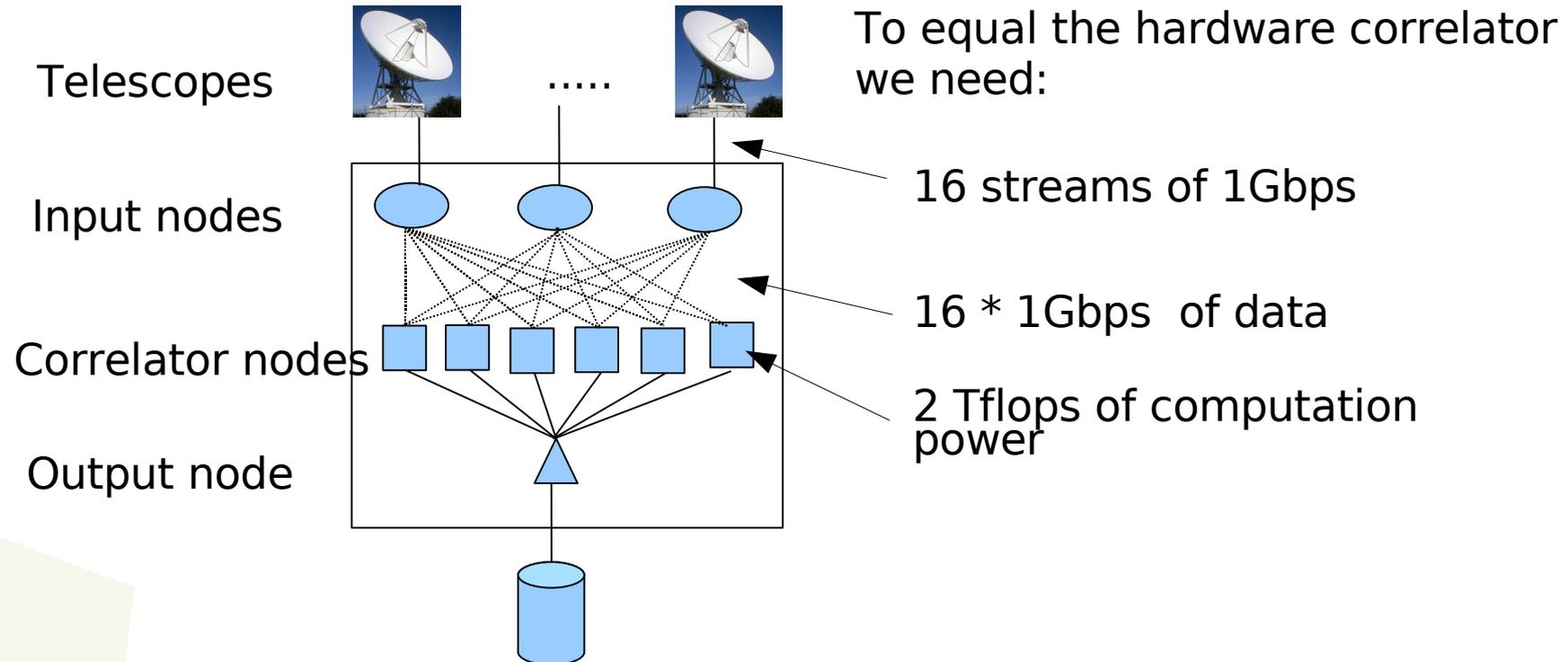


What is drawn in this picture is a graph with:

- **Node that represents computation process**
- **Edges that represents streams of data between the computation process**

SCARLe

An exemple of usage of dynamic network for static application



By knowing the number of antenna, the number of channels it is relatively easy to estimate for all Edges and Nodes of this graph the amount of resources needed.

The application has *STATIC Requirement*

First version of SCARIE on top of Starplane:

- 1) we provide a description of the application topology;

```
import SCARIE_ASE
from SCARIE_ASE import *

Experiment1 = Begin("Experiment1")
Constraint("starttime", "08/09/1979")
Constraint("entime", "09/09/1979")
Constraint("nice", "realtime(I want it all)")

Radiotelescope("Haystack-RT0", bandwidth="1024")
Radiotelescope("Haystack-RT1", bandwidth="1024")

InputNode("in/1", CPU="2Ghz")
InputNode("in/2", CPU="2Ghz")
ComputeNode("cn/1", CPU="1Ghz")
ComputeNode("cn/2", CPU="1Ghz")
ComputeNode("cn/3", CPU="1Ghz")
ComputeNode("cn/4", CPU="1Ghz")
OutputNode("out/1", [])

Link("in/1", "Haystack-RT0", bandwidth="1024")
Link("in/2", "Haystack-RT1", bandwidth="1024")

Link("in/1", "cn/1", bandwidth="256")
Link("in/1", "cn/2", bandwidth="256")
Link("in/1", "cn/3", bandwidth="256")
Link("in/1", "cn/4", bandwidth="256")

Link("in/2", "cn/1", bandwidth="256")
```

← Example of AST

← List of point2point channels

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Link("in/2", "cn/1", bandwidth="256" )
```

Element that should be stucked to specific resource.

Location-free elements

First version of SCARIE on top of Starplane:

- 1) Channels are expressed, we have a topological description of the application (AST).
- 2) The AST is submitted to the resource scheduler...
- 3) a *Resource Mapping* file is returned containing:
 - for each computation process a computing node.
 - for each channel in the request the network path that is supposed to be used.
- 4) When the application is started:**
 - we are sure that the resources are available;
 - we are sure that the application fit into the resource required.
 -this is good for real-time application...

Second version of SCARIE on top of Starplane: how to make a a better demonstration of the dynamic capabilities of Starplane.

The idea... SFXC use time slicing to distribute job.

At cluster level:

- timeslice is used to distribute computation

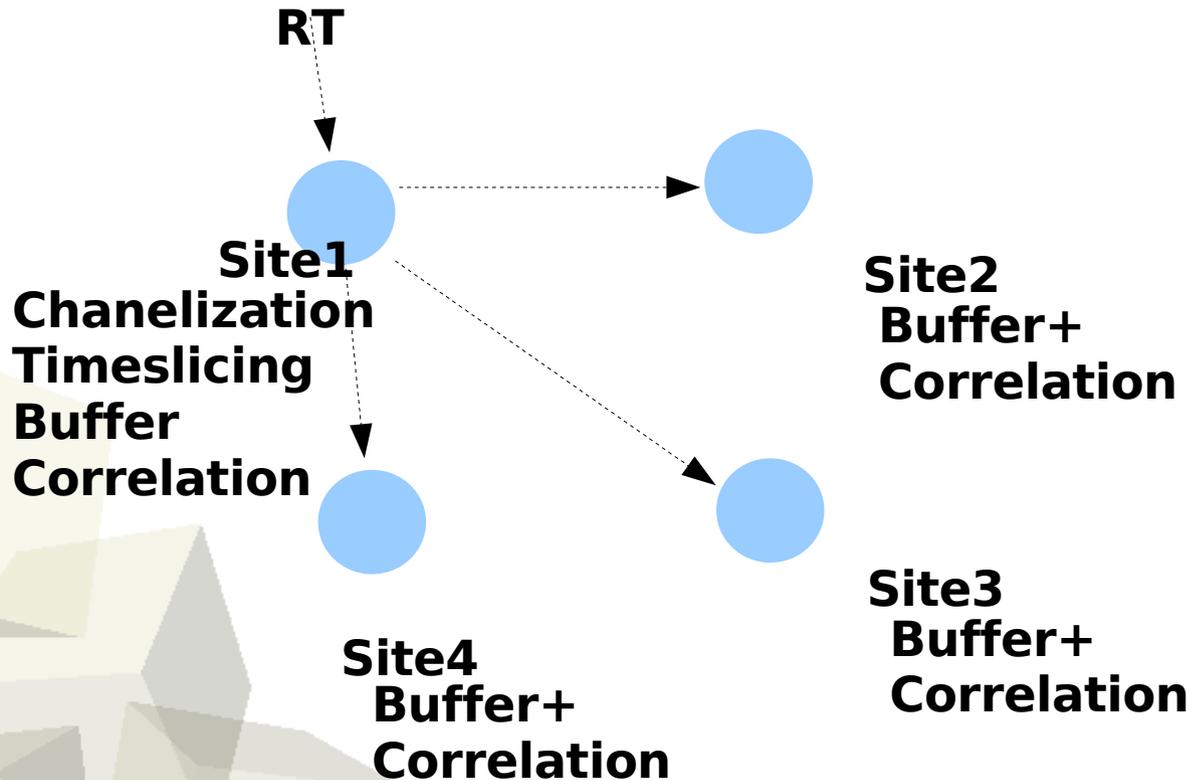
At grid level:

- chunk of timeslices.

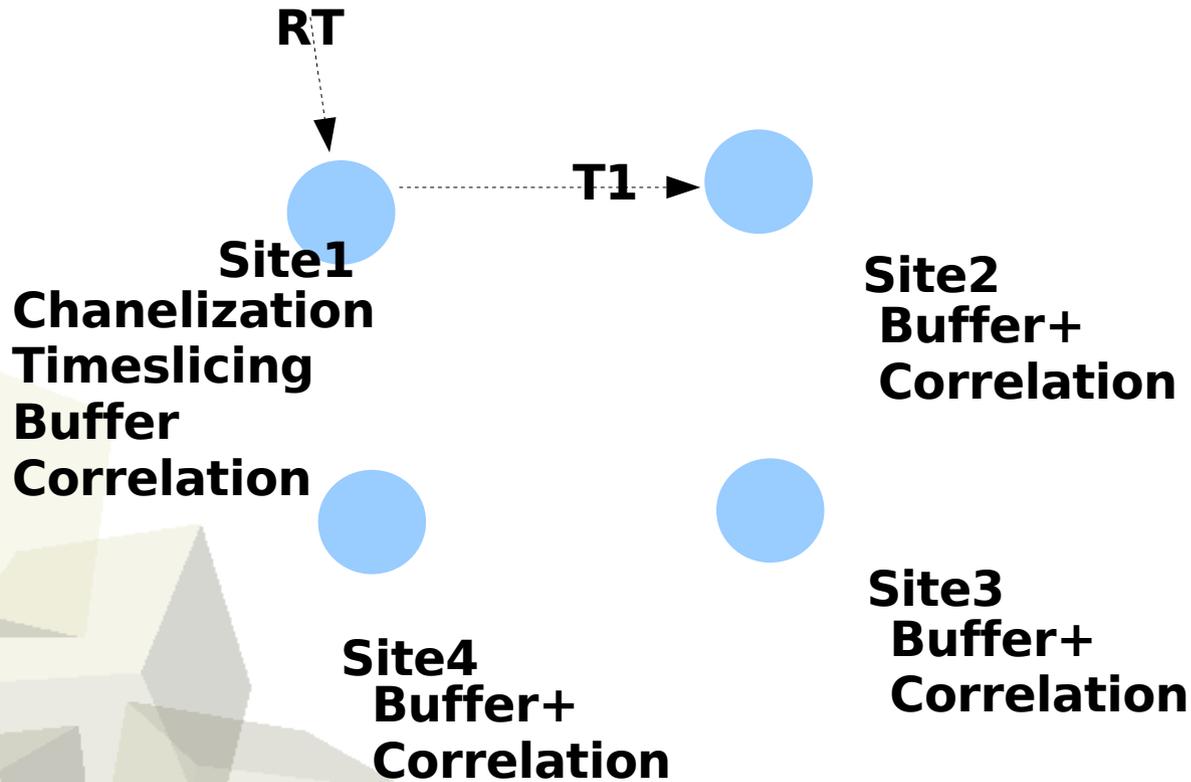
How can we distribute timeslices sequentially over the different cluster sites ?

Second senario of SCARIE on top of Starplane:

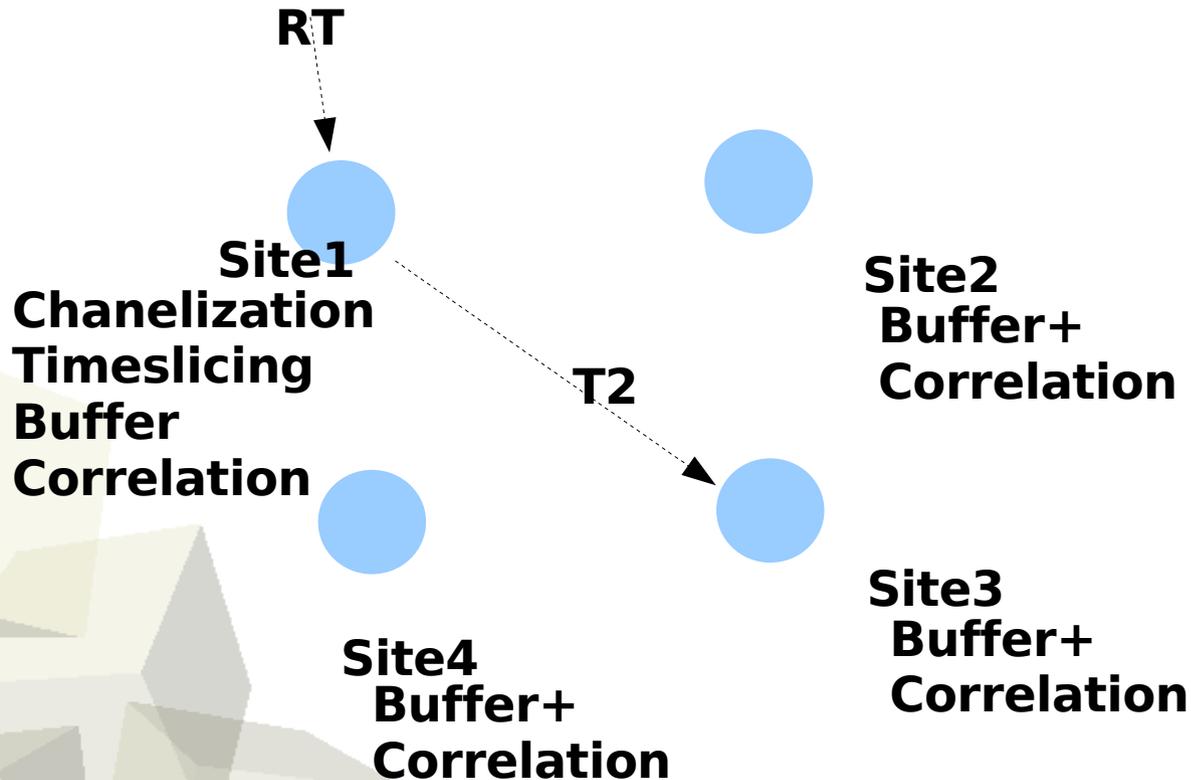
An attempt to a better demonstration of the dynamic capabilities of Starplane.



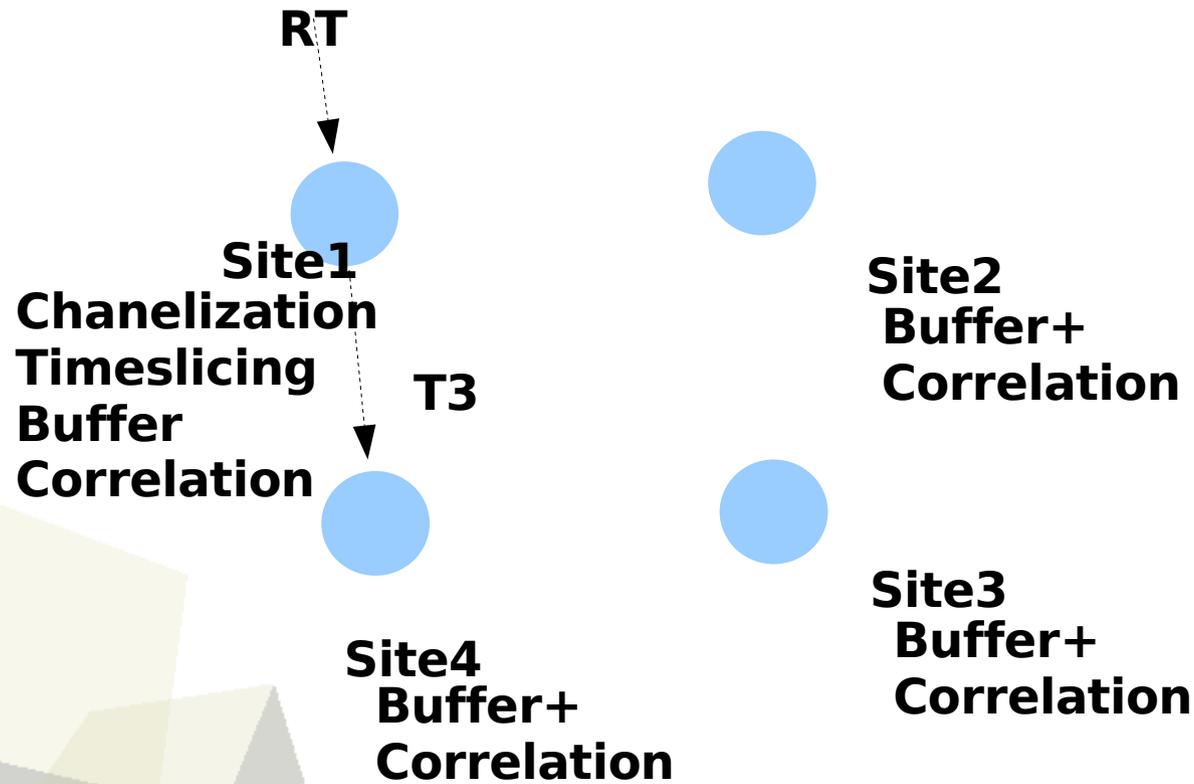
Second senario of SCARIE on top of Starplane:



Second senario of SCARIE on top of Starplane:



Second senario of SCARIE on top of Starplane:



Second senario of SCARIE on top of Starplane:

This demonstrate the dynamically controlled lighpath of Sta

**Fast light-path modification allow to keep the size of the bu
small (less than the main memory of the nodes: 4GB);**

Inter-site communication is only streaming, no message dia

**Load distribution can be adapted by selecting different size
timeslices;**

That is all for me...

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What about a demo of this for SC07 ?

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What do we want to demonstrate ?

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